Validation Methods

Simons Electron Microscopy Center Winter EM Course 2016-17

The dark side of single-particle EM

Every data set and processing approach yields a 3D structure ! The great thing about single-particle EM:

Every data set and processing approach yields a 3D structure ! The bad thing about single-particle EM:

But is it correct ???



Particularly problematic for low-resolution maps







Potential issues:

Heterogeneity - Compositional - Conformational - Discrete states

Effect of cross-linking

- Continuous movement

The β₂V₂R-βarrestin1-Fab30 complex **Effect of cross-linking:**



Shukla etal. (2014) Nature 512: 218-222

The HOPS tethering complex **Effect of cross-linking:**

Cross linked

Native



Bröckeretal. (2012) PNAS <u>109</u>: 1991-1996

Chou etal. (2016) NSMB <u>23</u>: 761-763



Specimen preparation

Potential issues:

No particles
Preferred orientations

Potential issues with grids

No particles (particles bind to carbon and avoid holes)

- Increase protein concentration
- Double blotting
- PEG treatment of grid
- Use thin carbon film

Preferred orientation (particles align at air/water interface)

– non-isotropic resolution of the density map Lack of views will result in:

The mTOR1 complex



Potential issues with grids

No particles (particles bind to carbon and avoid holes)

- Increase protein concentration
- Double blotting
- PEG treatment of grid
- Use thin carbon film

Preterred orientation (particles align at airwater interface)

Lack of views will result in:

- non-isotropic resolution of the density map
- can potentially lead to an incorrect density map

- Use thicker (or thinner) ice

— Use gold grids (Russo & Passmore (2014) Science <u>346</u>: 1377-1380) . Use thin carbon film (commonly used for nbosome samples) Use low concentration of detergent (changes surface tension)

å

Preferred orientations: Pex1/6 complex Without detergent



Preferred orientations: Pex1/6 complex With detergent



Potential issues:

– Low contrast – Beam damage

Potential issues with images

Poor electron scattering high electron dose





→ low electron dose Beam sensitivity

 \rightarrow Loss of information cannot be fixed

→ Electron micrographs recorded with low electron doses
→ Particles hard too see, especially small ones

Problem fixed by DDD cameras

→ Collect long movies
→ Add frames with resolution filter



Potential issues:

Particle picking: - Model/reference bias

2D classification:

– Model/reference bias

Number of classes

- Heterogeneous classes

- Disappearing classes

<u>Potential issues with particle picking</u>





1,000 images containing pure white noise

Henderson (2013)Proc. Natl. Acad. Sci. USA 110: 18037-18041

Shatsky et al. (2009) J. Struct. Biol. <u>166</u>:67-78

Albert Einstein

Potential issues with particle picking



Model/reference bias

an image of Albert Einstein Average of 1,000 images containing <u>pure white noise</u> after alignment to

 \rightarrow Einstein from noise

Henderson (2013)Proc. Natl. Acad. Sci. USA 110: 18037-18041

Shatsky et al. (2009) J. Struct. Biol. <u>166</u>:67-78

Potential issues with particle picking

Mao etal. (2013) HV env himer

Henderson (2013) PNAS <u>110</u>: 18037-18041

PNAS 110: 12438-12443



Henderson (2013) PNAS <u>110</u>: 18037-18041

→ Averages will end up looking like templates used for particle picking

Using template matching to pick particles from very noisy images is dangerous

Mao etal. (2013) PNAS <u>110</u>: 12438-12443

HJV env trimer

Structure determination by single-particle EM

Potential issues with particle picking

Potential issues with 2D classification (K-means)

K-means classification needs to be initialized with a numberot classes K

- Deterministic initialization
- K templates are provided

(supervised classification, multi-reference classification)

- \rightarrow reference bias \rightarrow Einstein from noise
- Random initialization
- K images are randomly chosen and used as references
- data set is randomly split into K classes and class averages are used results tend to be unstable (different results for different repeats)

Potential issues with 2D classification (K-means)

Properties /issues of K-means classification

- the algorithm always converges, butnot necessarily to the global optimum (the best possible solution)
- outliers (rare objects whose appearance is partially or entirely unrelated to that of the bulk of the data) have a very negative impacton the outcome
- problem of "group collapse", i.e., the possibility of a group losing its members to the point of vanishing
- if the numberofgroups is notguessed correctly and the groups the result depends dramatically on the initialization are notwell separable (always the case for very noisy data),

Potential issues with 2D classification (K-means)

Berative stable alignment and clustering (ISAC) procedure Yang etal. (2012) Structure 20: 237-247

- Equal-size group K-means classification
- → prevents group collapse
- Assessmentthatalignmentparameters for images in a cluster are stable (below a pixel error threshold) in repetitions
- Assessmentthat classes are reproducible in repetitions
- ightarrow classes are stable and reproducible
- Iclasses are homogeneous = good for 3D reconstruction
- Only a fraction of the data set is assigned to classes
- Computationally very expensive



Potential issues:

Incorrect map

- Because of:
- Heterogeneous sample
- Missing views
- Incorrect solution



Single particles in ice



Angular reconstitution



van Heel, 1987

- 1. choose 3 projection images that are perpendicular views of the particle (anchor set)
- 2. add in further projections and keep refining



Serysheva etal., 1995

Chicken Slo2.2 in the absence of Na⁺



VIPER

Stochastic Hill Climbing

(initially introduced in program SIMPLE)

Initial model (obtained with VIPER)

Class averages



Angular refinement



Chicken Slo2.2 in the absence of Na⁺



VIPER

Stochastic hill climbing

Similar principles as used in ISAC: - stability and reproducibility

assessments

cryoSPARC

Class averages

Initial model (obtained with VPER)



Potential issues with density map



Model/reference bias

an image of Albert Einstein pure white noise after alignment to Average of 1,000 images containing

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Henderson (2013)Proc. Natl. Acad. Sci. USA 110: 18037-18041 Shatsky et al. (2009) J. Struct. Biol. <u>166</u>:67-78



Potential issues with density map



Model/reference bias

an image of Albert Einstein <u>pure white noise</u> after alignment to Average of 1,000 images containing

 \rightarrow Einstein from noise

otnoise resolution features due to alignment Over-fitting results in spurious high-

Henderson (2013)Proc. Natl. Acad. Sci. USA 110: 18037-18041

Shatsky et al. (2009) J. Struct. Biol. <u>166</u>:67-78



Resolution assessment



Resolution assessment



Resolution assessment





Local resolution

Resolution is justa number

Even "gold standard" FSC can give overestimated resolution

"Gold standard" FSC is not the only valid resolution assessment

Resolution assessment



20 Å

Rotavirus double-layered particle

3.8 A°

> 20 Å protein envelope

~ 9-10 Å a helices

~4 Å bulky side chains

Rosenthal & Rubinstein (2015) Curr. Opin. Struct. Biol. <u>34</u>: 135-144

2.6 Å

eta -sheets

.4.8 Å

Validation		Final 3D map	3D classification Refinement	Initial 3D map	3D reconstruction	 2D classification 2D averages 	Particle picking Alignment	2D images	Grid	Specimen preparation	Protein	Expression Purification	Cells	tructure determination
														by single-particle EM



Map validation

Meeting of experts in 2010 to come up with standards for map validation

Outcome summarized in 2012:

Structure Meeting Review



Validation Task Force Meeting Outcome of the First Electron Microscopy

Jasmine Young,⁵ Helen M. Berman,⁵ Wah Chiu,³ Gerard J. Kleywegt,²⁰ and Catherine L. Lawson^{5,*} Gunnar F. Schröder,¹⁶ Alasdair C. Steven,¹⁷ David L. Stokes,¹⁸ John D. Westbrook,⁵ Willy Wriggers,¹⁹ Huanwang Yang,⁵ Richard Henderson,¹ Andrej Sali,² Matthew L. Baker,³ Bridget Carragher,⁴ Batsal Devkota,⁵ Kenneth H. Downing,⁶ Edward H. Egelman,⁷ Zukang Feng,⁵ Joachim Frank,^{8,9} Nikolaus Grigorieff,¹⁰ Wen Jiang,¹¹ Steven J. Ludtke,³ Ohad Medalia,^{12,21} Pawel A. Penczek,¹³ Peter B. Rosenthal,¹⁴ Michael G. Rossmann,¹⁵ Michael F. Schmid,³

Henderson etal. (2012) Structure <u>20</u>: 205-214

Map validation

- Compare reference-free averages with projections

Henderson etal. (2012) Structure 20: 205-214



Re-projections and angular distribution Map validation

Map validation

- Compare reference-free averages with projections
- only checks consistency of 3D map with 2D data
- also check angle distribution
- Tilt-pair analysis

Henderson etal. (2012) Structure 20: 205-214



Map validation Tilt-pair analysis



Map validation

Rosenthal & Rubinstein (2015) Curr. Opin. Struct. Biol. <u>34</u>: 135–144

Map validation Tilt-pair analysis

Henderson et al. (2011) J. Mol. Biol. <u>413</u>: 1028-1046

Table 1. Overview of tilt-pair statistics

		Particle size	Molecular mass	Number of	Number of	Successful	Anguli	ar error (°)
Specimen	Symmetry	(Å)	(MDa)	tilt pairs	particles	alignment (%)	Mean	Maximum
Rotavirus DLP	12	700	50	10	95	100/100	0.25	1.0
CAV	12	255	2.7	1	45	62/82	2.5	з.5
70S ribosomes	0	270×260	2.6	12	220	45/75	4.0	5.0
FAS	D3	260×220	2.6	2	44	59/95	4.0	6.0
PDH-E2CD	11	280	1.6	1	50	62/94	3.0	4.0
Thermus V-ATPase	C1	250×140	0.6	1	50	54/80	10.0	16.0
Bovine F-ATPase	C1	250×140	0.6	1	29	52/79	20.0	25.0
DNA-PKcs	C1	150×120	0.47	14	108	44/81	15.0	17.0
β-Galactosidase	D2	$180 \times 130 \times 95$	0.45	2	119	74/91	10.0	14.0

- determines whether overall 3D map is correct at 15-20 Å resolution (but not high-resolution features)
- allows determination of handedness
- allows as left find not of nativeanless
- I can be used to refine parameters used for orientation determination ightarrow can thus be used to improve the map
- validates orientation parameters (but not microscope parameters, i.e., defocus, magnification)
- "If less than 60% of particles show a single cluster, the basis for poor orientation parameters should be investigated"



Tilt-pair web server Map validation

Input

Load previous settings

20

10

30

Output

85

8

20

		orrection	Disable CTF o		
⊳	30.0	degrees	55.7	pixels	0.0
	Max resolution	lism	Angle astigma	radius)	article size (
⊳	100.0	A	59084.0	κv	100.0
	Min resolution		Defocus 2		oltage
degree	20.0	A	58626.0	A/px	.98
Зe	Tilt search rang		Defocus 1		agnification

τ

Stack 2 (max 300 particles) Stack 1 (max 300 particles) 3D model Browse... e2map.mrc Browse... stack1.mrc

Input data

-20 -10

Tilt about Y axis 0

Tilt about Y axis

0

39

10

23 19

ģ -10 Tilt about X axis 0

10

20

30

45 50 55 60 65 20 75 80

-30

30

-20

-10

0

10

20

30

Tilt about X axis

-20

1

10 38 -10

30

ά

Parameters:

Voltage Astigmatism Defocus Magnification Tilt Range **Resolution Range**

Effective binning: Optimized box size (after binning) Particle radius

Wasilewski & Rosenthal (2014) J. Struct. Biol. <u>186</u>: 122-131

Parameters format

Parameters for the Stack

Browse... stack1.par

Browse... stack2.mrc

Frealign

N 46 30 300 KV 55.7 A/px

average phase residual: $1 \stackrel{?}{=} 4 \stackrel{?}{=} 5 \stackrel{?}{=} 8 \stackrel{?}{=} 9 \stackrel{10}{=} 13 \stackrel{14}{=} 14 \stackrel{17}{=} 18 \stackrel{20}{=} 21 \stackrel{22}{=} 22 \stackrel{25}{=} 26 \stackrel{27}{=} 27 \frac{28}{=} 29 \stackrel{20}{=} 31 \stackrel{33}{=} 34 \stackrel{34}{=} 46 \stackrel{47}{=} 48 \stackrel{49}{=} 9$ Particles outside the cluster: $3 \stackrel{11}{=} 112 \stackrel{15}{=} 19 \stackrel{23}{=} 24 \stackrel{24}{=} 32 \stackrel{33}{=} 36 \stackrel{37}{=} 38 \stackrel{39}{=} 40 \stackrel{41}{=} 42 \stackrel{45}{=} 50$

Particles in the cluster (0.5o - 6.13°) near the minimum Average distance to the global minimum: 5.24°

100.0 - 30.0 A 58626 ; 59084

20 (effective: 10) px 4.98 (effective: 9.96)

> Minimum at the position: 2.0°, 10.0° Tilt axis (angle with respect to the X axis): 78.7° Minimal Phase Residual: 52.53° Hand Phase Difference: 12.48° Tilt angle: 10.2°

Summary of the results for all submitted particles:

http://www.ebi.ac.uk/pdbe/emdb/validation/tiltpain/ Map validation

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Map validation

- Compare reference-free averages with projections
- only checks consistency of 3D map with 2D data
- also check angle distribution
- Tilt-pair analysis
- excellent, also establishes handedness
- "Gold standard" FSC
- notnecessarily needed (but certainly notbad)
- Randomize phases

Henderson etal. (2012) Structure <u>20</u>: 205-214

Map validation Randomize phases

Rosenthal & Rubinstein (2015) Curr. Opin. Struct. Biol. <u>34</u>: 135-144 Chen etal. (2013) Ultramicroscopy <u>135</u>: 24-35

- Do single-particle reconstruction / refinement
- Determine resolution (FSC)
- below a threshold (75 or 80%) Take raw data, randomize phases beyond which FSC $_{T}$ falls
- Redo the same analysis and recalculate FSC curve
- Any signal in region of randomized phases indicates issues with noise alignment in that region
- Can be implemented in any package

Map validation Randomize phases

Rosenthal & Rubinstein (2015) Curr. Opin. Struct. Biol. <u>34</u>: 135-144 Chen etal. (2013) Ultramicroscopy <u>135</u>: 24-35



FSC signal due to true structural information

FSC signal due to over-fitting (noise)

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- Randomize phases
- excellent, but not commonly used

Appearance of expected secondary structure elements

Henderson etal. (2012) Structure <u>20</u>: 205-214



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- Evaluate with published information
- Appearance of expected secondary structure elements

Henderson etal. (2012) Structure <u>20</u>: 205-214

Evaluation with published information Map validation



Map validation

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- "Gold standard" FSC
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- Randomize phases
- excellent, but not commonly used
- Appearance of expected secondary structure elements
- Dock known atomic structures into map

Henderson etal. (2012) Structure <u>20</u>: 205-214

- cross-link mass spectrometry
- Evaluate with published information pull-down experiments
 - yeast two hybrid analysis















Map validation Docking of atomic models







Biol. Chem. <u>387</u>: 179-187

Nature 462: 745-758





Map validation - IP3 receptor New density map in 2011 at 11 Å resolution



Ludtke et al. (2011) Structure <u>19</u>: 1192-1199

Map validation - IP3 receptor Expected secondary structure elements



<u>Comparison of reference-free averages with projections</u> Map validation - IP3 receptor



- A: Map projection B: Reference-based class average
- C:Reference-free class average
- D: Selected particles

Mumay etal. (2013) Structure 21: 900-909





Map validation - IP3 receptor



Map validation - IP3 receptor 4.7 Å resolution structure