Validation Methods

Simons Electron Microscopy Center Winter EM Course 2015-16

The dark side of single-particle EM

The <u>great</u> thing about single-particle EM: Every data set and processing approach yields a 3D structure !

The <u>bad</u> thing about single-particle EM: Every data set and processing approach yields a 3D structure !

But is it correct ???



Particularly problematic for low-resolution maps

The issue: Structures of the IP3 receptor as determined by single-particle EM







Potential issues:

Heterogeneity – Compositional – Conformational – Discrete states – Continuous movement

Effect of cross-linking

Potential issues with samples

Before attempting structure determination – Understand and optimize your sample !

Prepare negatively stained specimens: Good contrast and preferred orientations → Easy to assess heterogeneity

If particles look heterogeneous: Calculate class averages → Assess type and degree of heterogeneity → Minimize heterogeneity by any means possible

If chemical fixation was used: Look at unfixed sample to assess effect of cross-linking → Assess whether structure of cross-linked sample is meaningful

Effect of cross-linking: The $\beta_2 V_2 R$ - $\beta_a rrestin1$ -Fab30 complex



Shukla et al. (2014) Nature 512: 218-222

Effect of cross-linking: The HOPS tethering complex

Cross-linked



Bröcker *et al.* (2012) *PNAS* <u>109</u>: 1991-1996

Native



Hui-Ting Chou unpublished



Potential issues:

- No particles
- Preferred orientations

Potential issues with grids

No particles (particles bind to carbon and avoid holes)

- Increase protein concentration
- Double blotting
- PEG treatment of grid
- Use thin carbon film

Preferred orientation (particles align at air/water interface) Lack of views will result in: – non-isotropic resolution of the density map

The mTOR1 complex



Yip et al. (2010) Mol. Cell 38: 768-774

Potential issues with grids

No particles (particles bind to carbon and avoid holes)

- Increase protein concentration
- Double blotting
- PEG treatment of grid
- Use thin carbon film

Preferred orientation (particles align at air/water interface)

Lack of views will result in:

- non-isotropic resolution of the density map

- can potentially lead to an incorrect density map

- Use thicker (or thinner) ice

- Use low concentration of detergent (changes surface tension)

- Use thin carbon film (commonly used for ribosome samples)

- Use gold grids (Russo & Passmore (2014) Science 346: 1377-1380)

Preferred orientations: Pex1/6 complex Without detergent



Preferred orientations: Pex1/6 complex With detergent





Potential issues:

Low contrast

– Beam damage

Potential issues with images

Poor electron scattering \rightarrow high electron dose



Beam sensitivity → low electron dose

→ Poor SNR can be fixed by averaging → Loss of information cannot be fixed

→ Electron micrographs recorded with low electron doses
→ Particles hard too see, especially small ones

Problem fixed by DDD cameras

 \rightarrow Collect long movies \rightarrow Add frames with resolution filter



Potential issues:

- Particle picking:
- Model/reference bias
- 2D classification:
- Model/reference bias
- Number of classes
- Heterogeneous classes
- Disappearing classes

Potential issues with particle picking





1,000 images containing pure white noise Reference: <u>Albert Einstein</u>

Shatsky *et al.* (2009) *J. Struct. Biol.* <u>166</u>: 67-78 Henderson (2013) *Proc. Natl. Acad. Sci. USA* <u>110</u>: 18037-18041

Potential issues with particle picking



Model/reference bias

Average of 1,000 images containing pure white noise after alignment to an image of Albert Einstein

 \rightarrow Einstein from noise

Shatsky *et al.* (2009) *J. Struct. Biol.* <u>166</u>: 67-78 Henderson (2013) *Proc. Natl. Acad. Sci. USA* <u>110</u>: 18037-18041

Potential issues with particle picking



Mao *et al.* (2013) *PNAS* <u>110</u>: 12438-12443



Henderson (2013) *PNAS* <u>110</u>: 18037-18041

Potential issues with particle picking



Using template matching to pick particles from very noisy images is dangerous

→ Averages will end up looking like templates used for particle picking

Mao *et al.* (2013) *PNAS* <u>110</u>: 12438-12443

Henderson (2013) *PNAS* <u>110</u>: 18037-18041

Potential issues with 2D classification (K-means)

K-means classification needs to be initialized with a number of classes *K*

- Deterministic initialization
 - K templates are provided
 - (supervised classification, multi-reference classification)
 - \rightarrow reference bias \rightarrow Einstein from noise
- Random initialization
 - *K* images are randomly chosen and used as references
 - data set is randomly split into K classes and class averages are used \rightarrow results tend to be unstable (different results for different repeats)

Potential issues with 2D classification (K-means)

Properties / issues of *K*-means classification

- the algorithm always converges, but not necessarily to the global optimum (the best possible solution)
- outliers (rare objects whose appearance is partially or entirely unrelated to that of the bulk of the data) have a very negative impact on the outcome
- problem of "group collapse", i.e., the possibility of a group losing its members to the point of vanishing
- if the number of groups is not guessed correctly and the groups are not well separable (always the case for very noisy data), the result depends dramatically on the initialization

Potential issues with 2D classification (K-means)

Iterative stable alignment and clustering (ISAC) procedure Yang *et al.* (2012) *Structure* <u>20</u>: 237-247

- Equal-size group *K*-means classification
 - \rightarrow prevents group collapse
- Assessment that alignment parameters for images in a cluster are stable (below a pixel error threshold) in repetitions
- Assessment that classes are reproducible in repetitions
 - \rightarrow classes are stable and reproducible
 - \rightarrow classes are <u>homogeneous</u> = good for 3D reconstruction
 - Only a fraction of the data set is assigned to classes
 - Computationally very expensive



Potential issues:

Incorrect map

Because of:

- Heterogeneous sample
- Missing views
- Incorrect solution

Random conical tilt reconstruction



Single particles in ice



Angular reconstitution



van Heel, 1987

- 1. choose 3 projection images that are perpendicular views of the particle (anchor set)
- 2. add in further projections and keep refining



Serysheva et al., 1995

Chicken Slo2.2 in the absence of Na⁺



VIPER

Similar principles as used in ISAC:

stability and reproducibility assessments

Class averages Initial model (obtained with VIPER)



Potential issues:

Reference bias

Overfitting

Resolution assessment

Potential issues with density map



Model/reference bias

Average of 1,000 images containing pure white noise after alignment to an image of Albert Einstein

 \rightarrow Einstein from noise

Over-fitting results in spurious highresolution features due to alignment of noise

Shatsky *et al.* (2009) *J. Struct. Biol.* <u>166</u>: 67-78 Henderson (2013) *Proc. Natl. Acad. Sci. USA* <u>110</u>: 18037-18041

Resolution assessment



Maps have to be independent !

FSC = 0.143 Phase error = 60° Rosenthal & Henderson (2003) *J. Mol. Biol.* <u>333</u>: 721-745

Resolution assessment



Resolution assessment





"Gold standard" FSC is not the only valid resolution assessment

Even "gold standard" FSC can give an overestimated resolution

Resolution is just a number

Local resolution

Resolution assessment

What should be resolved ?

> 20 Å protein envelope

~ 9-10 Å α -helices

< 4.8 Å β -sheets

~ 4 Å bulky side chains



Rosenthal & Rubinstein (2015) Curr. Opin. Struct. Biol. 34: 135-144



The issue: Structures of the IP3 receptor as determined by single-particle EM





Meeting of experts in 2010 to come up with standards for map validation

Outcome summarized in 2012:





Outcome of the First Electron Microscopy Validation Task Force Meeting

Richard Henderson,¹ Andrej Sali,² Matthew L. Baker,³ Bridget Carragher,⁴ Batsal Devkota,⁵ Kenneth H. Downing,⁶ Edward H. Egelman,⁷ Zukang Feng,⁵ Joachim Frank,^{8,9} Nikolaus Grigorieff,¹⁰ Wen Jiang,¹¹ Steven J. Ludtke,³ Ohad Medalia,^{12,21} Pawel A. Penczek,¹³ Peter B. Rosenthal,¹⁴ Michael G. Rossmann,¹⁵ Michael F. Schmid,³ Gunnar F. Schröder,¹⁶ Alasdair C. Steven,¹⁷ David L. Stokes,¹⁸ John D. Westbrook,⁵ Willy Wriggers,¹⁹ Huanwang Yang,⁵ Jasmine Young,⁵ Helen M. Berman,⁵ Wah Chiu,³ Gerard J. Kleywegt,²⁰ and Catherine L. Lawson^{5,*}

Henderson et al. (2012) Structure 20: 205-214



- Compare reference-free averages with projections

Henderson et al. (2012) Structure 20: 205-214

Map validation

Re-projections and angular distribution





- Compare reference-free averages with projections
 - only checks consistency of 3D map with 2D data
 - also check angle distribution
- Tilt-pair analysis



Tilt-pair parameter plot Tilt-pair phase residual plot 15° 45° - 45° 0° 30° -30° – 15° TILTDIRECTION 90 degrees 45° 30° * ** * * 15° * 5 TILTDIRECTION 0° 180 degrees 0 degrees * – 15° D – 30° TILTANGLE=30. Y TILTANGLE=40. 0 45° ► X 270 degrees

Rosenthal & Rubinstein (2015) Curr. Opin. Struct. Biol. 34: 135-144

Henderson et al. (2011) J. Mol. Biol. 413: 1028-1046

Table 1	. Overview	of tilt-pair	statistics
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Specimen	Symmetry	Particle size (Å)	Molecular mass (MDa)	Number of tilt pairs	Number of particles	Successful alignment (%)	Angular error (°)	
							Mean	Maximum
Rotavirus DLP	<i>I</i> 2	700	50	10	95	100/100	0.25	1.0
CAV	I2	255	2.7	1	45	62/82	2.5	3.5
70S ribosomes	C1	270×260	2.6	12	220	45/75	4.0	5.0
FAS	D3	260×220	2.6	2	44	59/95	4.0	6.0
PDH-E2CD	<i>I</i> 1	280	1.6	1	50	62/94	3.0	4.0
Thermus V-ATPase	C1	250×140	0.6	1	50	54/80	10.0	16.0
Bovine F-ATPase	C1	250×140	0.6	1	29	52/79	20.0	25.0
DNA-PKcs	C1	150×120	0.47	14	108	44/81	15.0	17.0
β-Galactosidase	D2	$180\!\times\!130\!\times\!95$	0.45	2	119	74/91	10.0	14.0

- determines whether overall 3D map is correct at 15-20 Å resolution (but not high-resolution features)
- allows determination of handedness
- can be used to refine parameters used for orientation determination \rightarrow can thus be used to improve the map
- validates orientation parameters (but not microscope parameters, i.e., defocus, magnification)

"If less than 60% of particles show a single cluster, the basis for poor orientation parameters should be investigated"

Tilt-pair alignment test

angular errors for determination of the tilt transformation of each particle pair
 expected for random orientations



Rosenthal & Rubinstein (2015) *Curr. Opin. Struct. Biol.* <u>34</u>: 135-144 Baker *et al.* (2012) *Proc. Natl Acad. Sci. USA* <u>109</u>: 11675-11680 Russo & Passmore (2014) *J. Struct. Biol.* <u>187</u>: 112-118

Map validation Tilt-pair web server

Input



Output



Parameters:

-10

0

nification	4.98 (effective: 9.96) A/px
ocus	58626 ; 59084
gmatism	55.7
age	300 kV
olution Range	100.0 - 30.0 A
Range	30
icle radius	20 (effective: 10) px
mized box size (after iing)	46
ctive binning:	2

Summary of the results for all submitted particles:

Minimal Pha	se Residual: 52.53°
Minimum at	the position: 2.0°, 10.0°
Tilt axis (and	gle with respect to the X axis): 78.7°
Tilt angle: 1	0.2°
Hand Phase	Difference: 12.48°
Average dist	ance to the global minimum: 5.24°
Particles in t average pha	the cluster (0.5 σ – 6.13°) near the minimum se residual:
1 2 4 5 7 8 1 28 29 30 31	9 10 13 14 16 17 18 20 21 22 25 26 27 34 35 43 44 46 47 48 49
Particles out	side the cluster:
3 6 11 12 15 50	5 19 23 24 32 33 36 37 38 39 40 41 42 45

Wasilewski & Rosenthal (2014) J. Struct. Biol. 186: 122-131

Map validation

http://www.ebi.ac.uk/pdbe/emdb/validation/tiltpair/

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- Compare reference-free averages with projections
 - only checks consistency of 3D map with 2D data
 - also check angle distribution
- Tilt-pair analysis
 - excellent, also establishes handedness
- "Gold standard" FSC
 - not necessarily (but certainly not bad)
- Randomize phases

Henderson et al. (2012) Structure 20: 205-214

Map validation Randomize phases

Rosenthal & Rubinstein (2015) *Curr. Opin. Struct. Biol.* <u>34</u>: 135-144 Chen *et al.* (2013) *Ultramicroscopy* <u>135</u>: 24-35

- Do single-particle reconstruction / refinement
- Determine resolution (FSC)
- Take raw data, randomize phases beyond which $FSC_{\rm T}$ falls below a threshold (75 or 80%)
- Redo the same analysis and recalculate FSC curve
- Any signal in region of randomized phases indicates issues with noise alignment in that region
- Can be implemented in any package

Map validation Randomize phases

Rosenthal & Rubinstein (2015) *Curr. Opin. Struct. Biol.* <u>34</u>: 135-144 Chen *et al.* (2013) *Ultramicroscopy* <u>135</u>: 24-35



FSC signal due to over-fitting (noise)

FSC signal due to true structural information



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 - excellent, but not commonly used

Henderson et al. (2012) Structure 20: 205-214



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- Appearance of expected secondary structure elements

Henderson et al. (2012) Structure 20: 205-214

Map validation Expected secondary structure



Samso et al. (2009) PLoS Biol. 7: e1000085



- Compare reference-free averages with projections
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 - excellent, also establishes handedness
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- Randomize phases
 - excellent, but not commonly used
- Appearance of expected secondary structure elements
- Evaluate with published information

Henderson *et al.* (2012) *Structure* <u>20</u>: 205-214

Map validation

Evaluation with published information





- Compare reference-free averages with projections
 - only checks consistency of 3D map with 2D data
 - also check angle distribution
- Tilt-pair analysis
 - excellent, also establishes handedness
- "Gold standard" FSC
 - not necessarily (but certainly not bad)
- Randomize phases
 - excellent, but not commonly used
- Appearance of expected secondary structure elements
- Evaluate with published information
- Dock known atomic structures into map

Henderson *et al.* (2012) *Structure* <u>20</u>: 205-214









Tichelaar *et al*. (2004) *JMB* <u>344</u>: 435-442



Nakagawa *et al.* (2006) *Biol, Chem.* <u>387</u>: 179-187



Sobolevsky *et al.* (2009) *Nature* <u>462</u>: 745-758

Map validation - IP3 receptor Different maps of the IP3 receptor



Map validation – IP3 receptor New density map in 2011 at 11 Å resolution



Ludtke et al. (2011) Structure 19: 1192-1199

Map validation – IP3 receptor Expected secondary structure elements



Ludtke et al. (2011) Structure 19: 1192-1199

Map validation – IP3 receptor <u>Comparison of reference-free averages with projections</u>

Α	в	С	D
*	*	*	
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÷	*	30	
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- A: Map projection
- B: Reference-based class average
- C: Reference-free class average
- **D:** Selected particles

Murray et al. (2013) Structure 21: 900-909

Map validation - IP3 receptor <u>Tilt pair test</u>



Murray et al. (2013) Structure 21: 900-909

Map validation – IP3 receptor Comparison of maps from different programs



Map validation – IP3 receptor <u>4.7 Å resolution structure</u>



Fan et al. (2015) Nature 527: 336-341