

TimeScapes:
transforming timeseries
into spatial images

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General goal: discovering connections
between local and global processes

- Fast, local processes: $X_i(t)$
- Slow, global process: $a(t)$ (“activity function”)
- Ranking of the i^{th} process:

$$R_{X,a}(i) = I \left(\left| \frac{dX_i(t)}{dt} \right|, a(t) \right)$$

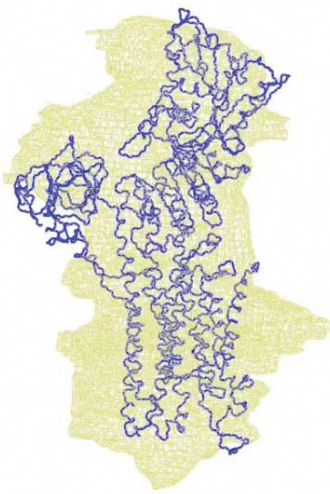
This ranking provides a measure of the relevance or contribution of each of the local processes $X_i(t)$ to the global process $a(t)$.

- I is a statistical measure of dependence, such as:
 - Pearson correlation coefficient (current release).
 - Mutual Information (in the upcoming release).

The approach is of general applicability

- The index i could correspond to any type of spatial attribute.
- It could also denote connections between pairs, triplets, ... of locations in space.
- Our applications will deal with single and pairwise locations.

Flexible fitting: DDFF and MDFF



Fitting of Ca-ATPase by
“Damped Dynamics Flexible Fitting”
(Kovacs et al., *Biophys. J.*, 2008)

MDFF is the best known and *de facto* approach for flexible fitting at atomic detail, but it requires a full MD trajectory.

As such, MDFF can benefit from the TimeScapes analysis presented here.

Application to Molecular Dynamics trajectories

- *TimeScapes* can perform two fundamental types of analyses on MD trajectories:
 1. Hinge-bending of protein molecules (“pivot analysis”).
 2. Pairwise residue distance geometry (“contact analysis”).
- The results of these analyses (i.e., the $R_{X,a}(i)$ as a function of i) can be mapped onto the 3D molecular structure for visualization.
- The “heat maps” thus obtained provide a picture of the regions of the molecule that are relevant for the significant events encoded in the long trajectory.

First step: calculation of the activity functions

- Three types of activity functions can be computed in *TimeScapes*:
 1. RMS fluctuations in a sliding time-window.
 2. Rate of contact-forming and -breaking events. This uses a coarse-grain model of 1 atom per side chain, and can be done by means of either of 2 types of graph:
 - a. A simple distance-cutoff graph;
 - b. A “Generalized Masked Delaunay” graph.
- This approach needs a preliminary smoothing of the distance time-series in order to suppress high-frequency noise.

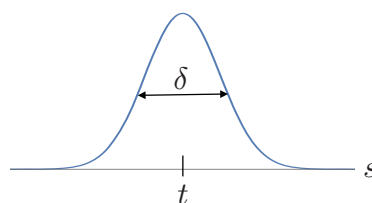
RMS fluctuation activity

- Computed as “standard deviation” of the whole ensemble of atomic Cartesian coordinates over a time-window centered at successive time frames. The values being averaged are weighted with a Gaussian function:

$$\sigma_i^2(t) = \sum_{s=t-\delta}^{t+\delta} \|p_i(s) - \bar{p}_i(t)\|^2 \cdot G(s-t) \quad \bar{p}_i(t) = \sum_{s=t-\delta}^{t+\delta} p_i(s) \cdot G(s-t)$$

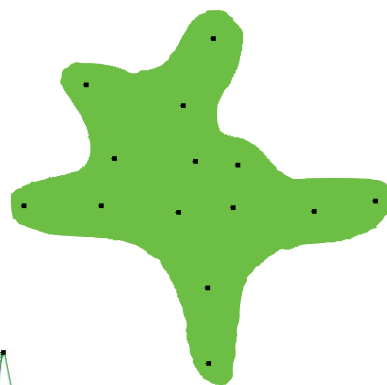
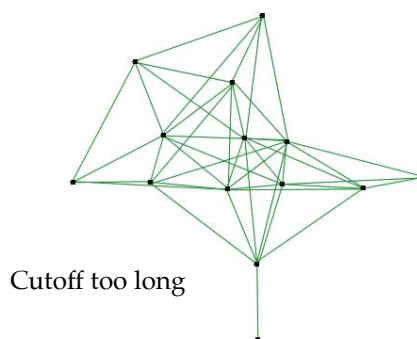
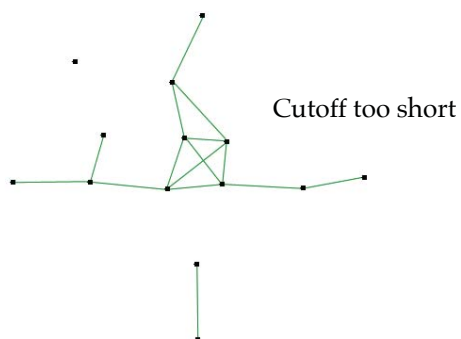
$$\text{RMS}(t) = \sqrt{\frac{1}{N} \sum_i \sigma_i^2(t)}$$

$G(s-t)$ = Gaussian whose FWHM is δ

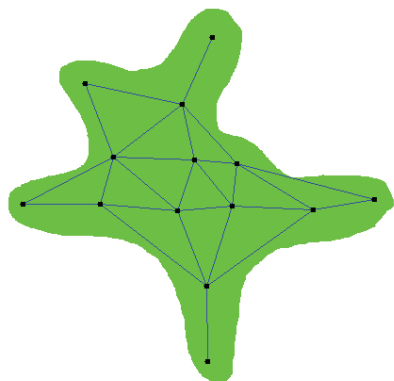


Simple distance-cutoff graph

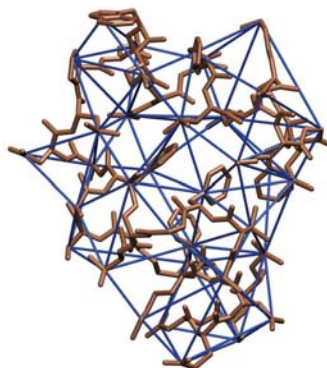
- Contacts are defined by pairs of representative atoms that are closer than a prescribed cutoff distance.
- Careful choice of the cutoff distance is important.



Generalized Masked Delaunay graphs (GMD)



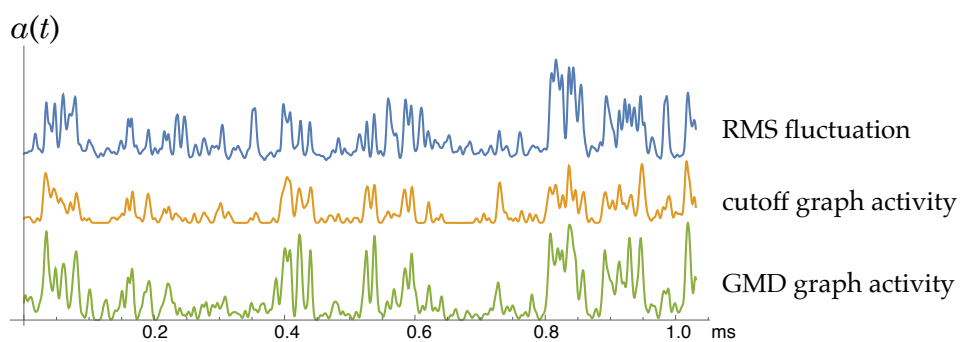
Masked Delaunay graph: masking out edges of the Delaunay graph not contained in the protein



3D example: Villin

The *Generalized* Masked Delaunay graphs are higher-order versions of the above, and are used to define a “contact metric” for a “recrossing filter”, which suppresses spurious events due to noise and sampling granularity. (Metric = smallest-order graph that contains a given edge.)

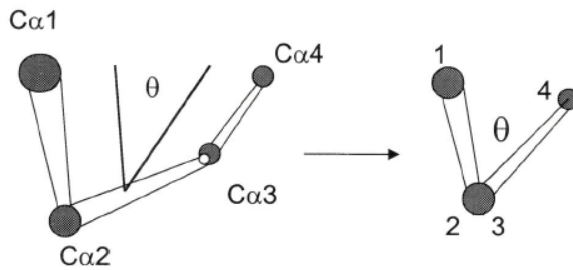
Example: activity measures for BPTI



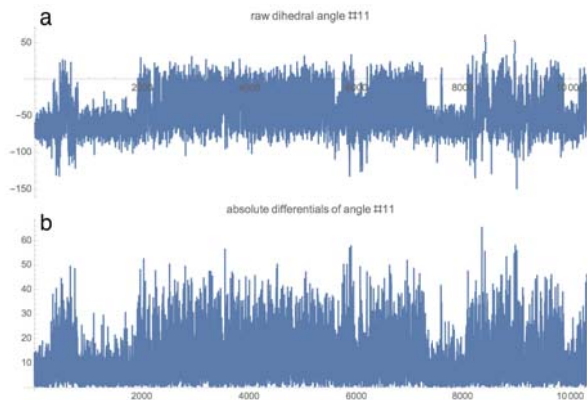
These three activity functions look very similar to one another. (But this isn't always the case; see Wriggers et al., *J. Chem. Theory Comput.*, 2009, 5:2595-2605.)

BPTI trajectory is from the *Anton* millisecond simulation from Shaw et al., 2010.

Pivot analysis: detection of hinging hot spots



Pseudo-dihedral angle θ generated by 4 consecutive $C\alpha$ atoms



a. Example of a particular pseudo-dihedral angle time series from the MD trajectory of BPTI.

b. The absolute values of its time differentials.

Pivot analysis: detection of hinging hot spots

For this, we apply our basic equation:

$$R_{X,a}(i) = I \left(\left| \frac{dX_i(t)}{dt} \right|, a(t) \right)$$

to the variables X_i = pseudo-dihedral angle # i ,

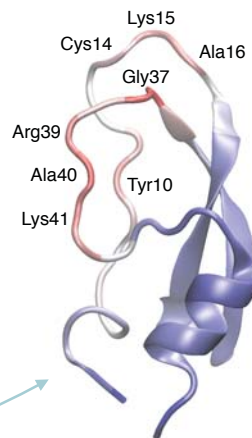
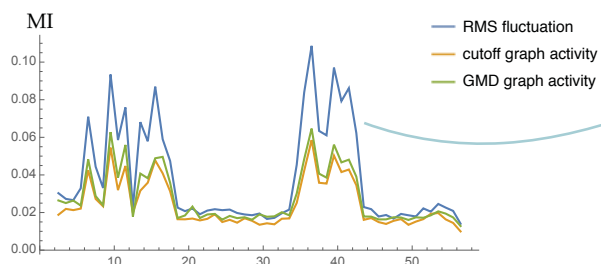
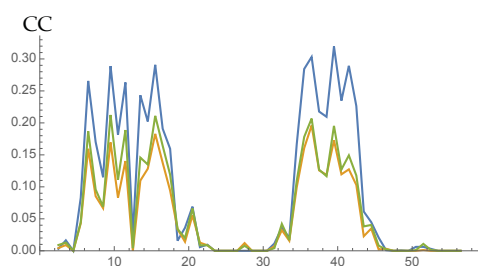
with I = either CC or MI,

and $a(t)$ = each of the 3 activity functions:

- RMS fluctuations
- cutoff graph
- GMD graph

Pivot analysis for BPTI

In this example, the 3 curves are very consistent:

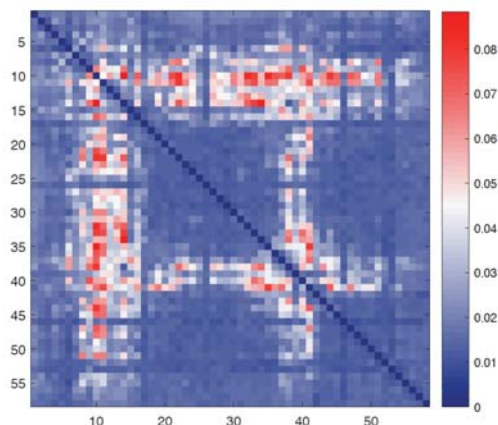


Heat map of pivot angle MI for RMS fluctuation

Contact analysis

Here, the index i ranges over *pairs* of residues, and the variable $X_i(t)$ is the distance between the corresponding pair of residues.

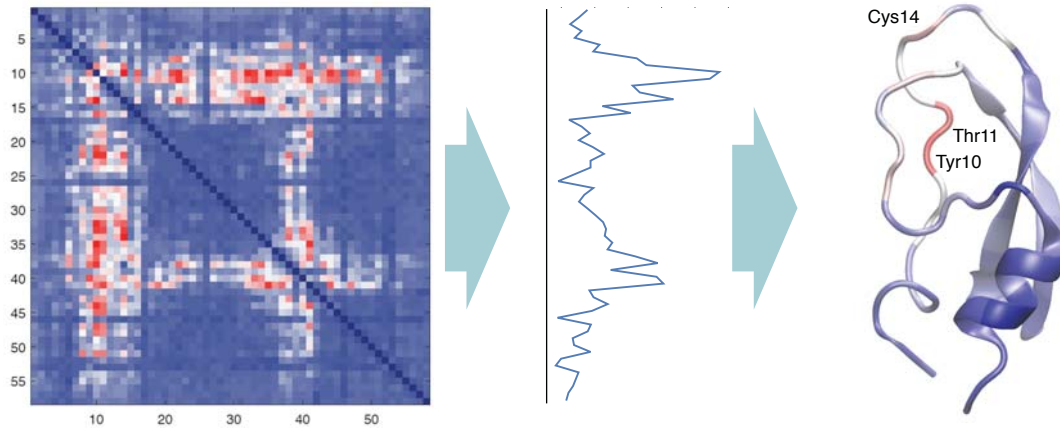
Then the ranking function $R_{X,\alpha}(i)$ can be displayed as a matrix:



MI contact matrix for BPTI, with $\alpha(t) = \text{RMS fluctuation}$

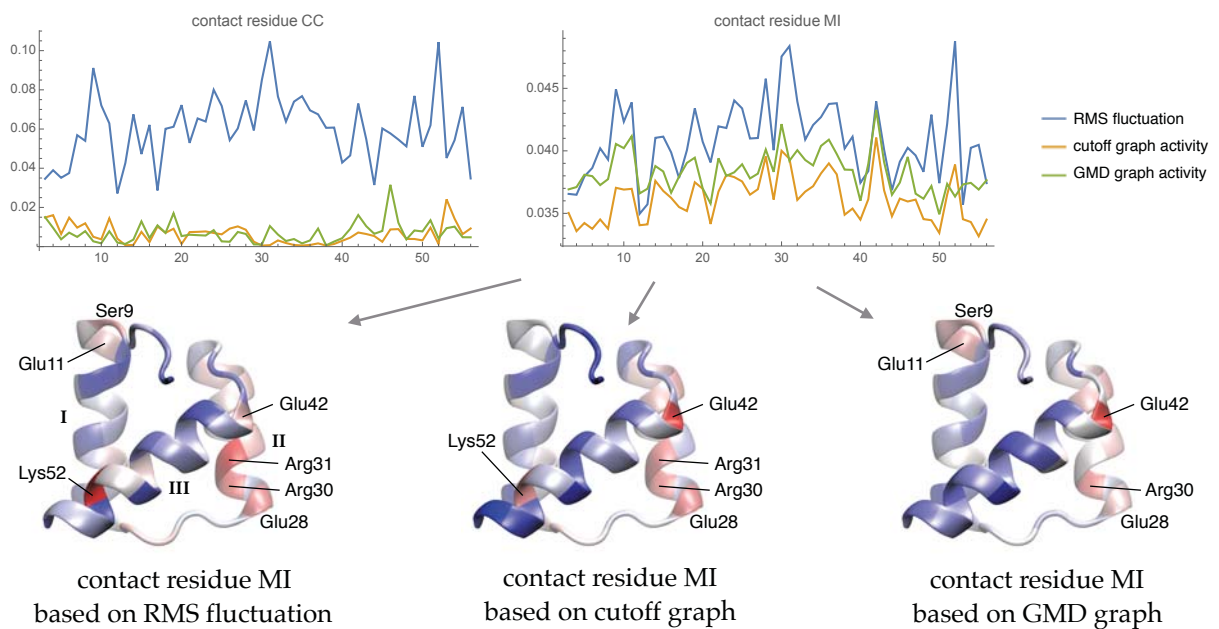
Contact analysis

This contact matrix is symmetric and has a banded structure. It can be projected onto either axis, and then mapped onto the 3D chain:



Outlook to Timescapes 1.4 (Summer 2016): Advantages of Nonlinear MI vs. Linear CC

We looked at a heat-induced unfolding trajectory of EnHD protein (Daggett lab, UW). CC profiles for graph-based activities were weak, while the MI results were more consistent with analysis based on RMS fluctuation activity:



Overview of the *TimeScapes* package

TimeScapes is a bundle of 10 Python programs. We will demonstrate the use of the following four:

- **agility.py**: computes the RMS fluctuation activity
- **terrain.py**: computes cutoff-based and GMD-based activities
- **tagging.py**: performs pairwise-residue contact-distance analysis, using the activity functions from **agility** or **terrain**
- **turning.py**: performs pivot-angle analysis, using the activity functions from **agility** or **terrain**

The last two programs also output PDB files containing the ranking coefficients in the B-factor field, for visualization purposes.

agility.py

The basic usage is:

```
agility.py infile1 infile2 delta outname
```

where:

infile1: PDB file, used for mass assignment and optional least-squares fit.

infile2: Trajectory file.

delta: Full Width at Half Maximum (FWHM) of Gaussian-weighted window.

$$\text{FWHM} = 2\sqrt{2 \ln 2} \sigma, \text{ where } \sigma \text{ is the standard deviation.}$$

outname: Basename prefix for output files.

terrain.py

The basic usage is:

```
terrain.py infile1 infile2 cut1 cut2 delta gtype outname
```

where:

`infile1`: PDB file, used for coarse-model assignment.

`infile2`: Trajectory file.

`cut1`: Values up to `cut1` are considered true contacts.

`cut2`: Values between `cut1` and `cut2` define the buffer zone in the recrossing filter, while values above `cut2` are considered non-contacts.

`delta`: Smoothing parameter for the Parzen window Gaussian function.

`gtype`: Graph type: either `GMD` or `Cutoff`.

`outname`: Basename prefix for output files.

tagging.py

The basic usage is:

```
tagging.py infile1 infile2 infile3 outname
```

where:

`infile1`: PDB file, used for coarse-model assignment.

`infile2`: Trajectory file.

`infile3`: Time series data file containing the activity function (typically the `xxx_segmentation.dat` output from `agility` or `terrain`)

`outname`: Basename prefix for output files.

turning.py

The basic usage is the same as for `tagging`:

```
turning.py infile1 infile2 infile3 outname
```

where:

`infile1`: PDB file, used for coarse-model assignment.

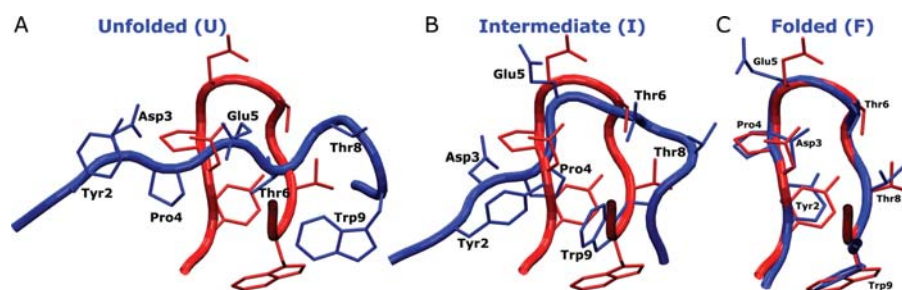
`infile2`: Trajectory file.

`infile3`: Time series data file containing the activity function (typically the `xxx_segmentation.dat` output from `agility` or `terrain`)

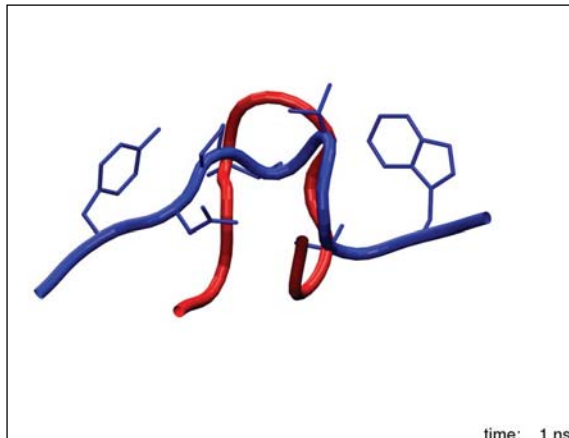
`outname`: Basename prefix for output files.

Running *TimeScapes* on the 'chignolin' trajectory

This is a 300 ns folding trajectory of a 10-residue peptide, using GaMD.



Running *TimeScapes* on the 'chignolin' trajectory



300 ns folding trajectory,
showing convergence to the
native PDB structure (red)

Running *TimeScapes* on the 'chignolin' trajectory

Go to the 'Extras' folder. It contains a bash script and data files.

The bash script
looks like:

```
#!/bin/bash
# Demo of TimeScapes 1.3 based on the chignolin trajectory
# Copyright Biomachina.org, 2016.

set -e
set -x

# adjust the version of gcc if needed:
: ${comp_version:=gcc-5.3.0}

for i in "$@"; do
  [[ $i == "*" ]] && eval $i
done

# adjust location of TimeScapes if needed, and uncomment your OS line:
# Mac:
prefix=$(greadlink -f ~/TimeScapes_1.3/objs/Darwin/x86_64/${comp_version})
# Cygwin:
# prefix=$(readlink -f ~/TimeScapes_1.3/objs/CYGWIN_NT-6.1/x86_64/${comp_version})
# Linux:
# prefix=$(readlink -f ~/TimeScapes_1.3/objs/Linux/x86_64/${comp_version})

PATH=${prefix}/bin:$PATH

mkdir -p timescapes_output
cd timescapes_output

agility.py ../demo.pdb ../demo.dcd 10 agility_10
terrain.py ../demo.pdb ../demo.dcd 2 3 10 GMD terrain_GMD_2_3_10
terrain.py ../demo.pdb ../demo.dcd 6 7 10 Cutoff terrain_Cut_6_7_10

tagging.py ../demo.pdb ../demo.dcd agility_10 segmentation.dat tagging_agil 2 0
tagging.py ../demo.pdb ../demo.dcd terrain_GMD_2_3_10 segmentation.dat tagging_terr_GMD 2 0
tagging.py ../demo.pdb ../demo.dcd terrain_Cut_6_7_10 segmentation.dat tagging_terr_Cut 2 0

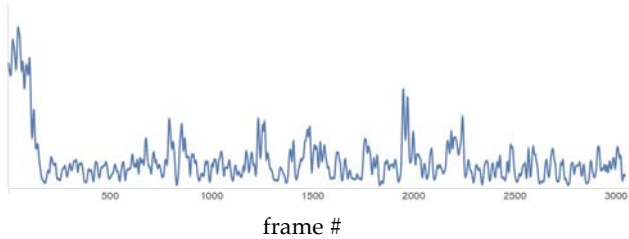
turning.py ../demo.pdb ../demo.dcd agility_10 segmentation.dat turning_agil
turning.py ../demo.pdb ../demo.dcd terrain_GMD_2_3_10 segmentation.dat turning_terr_GMD
turning.py ../demo.pdb ../demo.dcd terrain_Cut_6_7_10 segmentation.dat turning_terr_Cut

set +x
```

agility output files

agility_10_minima.log
 agility_10_segmentation.dat
 agility_10_transitions.log

RMS fluctuation activity file, used by tagging and turning



frame #	value	derivative
0	3.164843	0.000000
1	3.135847	-0.028997
2	3.103421	-0.032426
3	3.069534	-0.033887
4	3.036775	-0.032759
5	3.006153	-0.030622
6	2.978774	-0.027379
7	2.956830	-0.021944
8	2.940008	-0.016822
9	2.929659	-0.010348
10	2.929443	-0.000216
11	2.944859	0.015416
12	2.984017	0.039159
...

terrain output files

terrain_Cut_6_7_10_activity.dat
 terrain_Cut_6_7_10_events.log
 terrain_Cut_6_7_10_minima.log
 terrain_Cut_6_7_10_segmentation.dat
 terrain_Cut_6_7_10_transitions.log

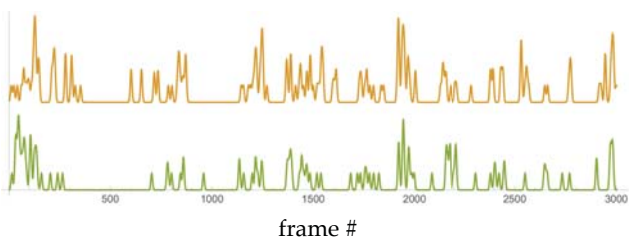
total, contact-forming, and -breaking activities (cutoff)

total activity and derivative (cutoff)

terrain_GMD_2_3_10_activity.dat
 terrain_GMD_2_3_10_events.log
 terrain_GMD_2_3_10_minima.log
 terrain_GMD_2_3_10_segmentation.dat
 terrain_GMD_2_3_10_transitions.log

total, contact-forming, and -breaking activities (GMD)

total activity and derivative (GMD)



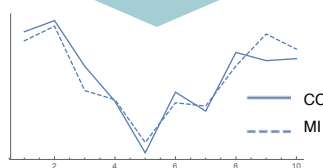
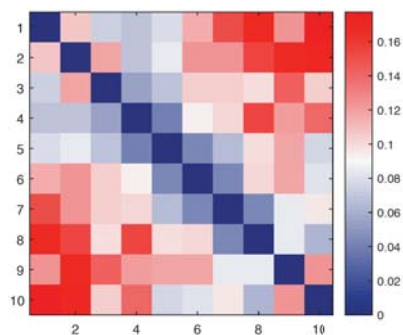
— cutoff graph activity
 — GMD graph activity

tagging output files

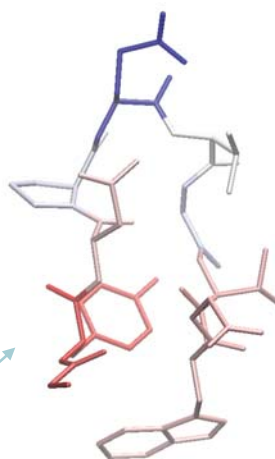
```
tagging_agil.log
tagging_agil_dump.dat
tagging_agil_pairwise.dat ← residue pairwise Pearson
tagging_agil_pairwise_resname.dat           correlation matrix
tagging_agil_pairwise_resname_count.dat
tagging_agil_pairwise_resname_max.dat
tagging_agil_pairwise_resname_normalized.dat
tagging_agil_projected.dat ← correlations projected
tagging_agil_projected.pdb ← to sequence
tagging_terr_Cut.log
tagging_terr_Cut_dump.dat
tagging_terr_Cut_pairwise.dat ← PDB file with the projected
tagging_terr_Cut_pairwise_resname.dat       correlations in the B-factor
tagging_terr_Cut_pairwise_resname_count.dat field. See in VMD.
tagging_terr_Cut_pairwise_resname_max.dat
tagging_terr_Cut_pairwise_resname_normalized.dat
tagging_terr_Cut_projected.dat ←
tagging_terr_Cut_projected.pdb ←
tagging_terr_GMD.log
tagging_terr_GMD_dump.dat
tagging_terr_GMD_pairwise.dat ←
tagging_terr_GMD_pairwise_resname.dat
tagging_terr_GMD_pairwise_resname_count.dat
tagging_terr_GMD_pairwise_resname_max.dat
tagging_terr_GMD_pairwise_resname_normalized.dat
tagging_terr_GMD_projected.dat ←
tagging_terr_GMD_projected.pdb ←
```

tagging: visualizing the output

tagging_agil_pairwise.dat



tagging_agil_projected.dat



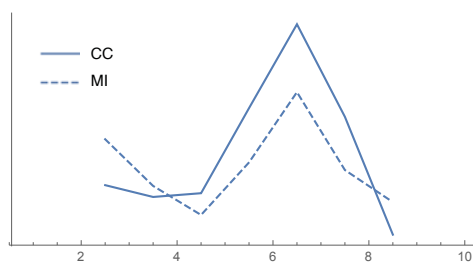
tagging_agil_projected.pdb

turning: output files



turning: visualizing the output

turning_agil_turning.dat



turning_agil_turning.pdb

